

# Distributed Synthesis of First Order Specifications for Agents with Partial Information

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## Distributed setting

- Infinite set  $\mathcal{A}$  of agents with unique id ; Finite set of actions  $\Sigma$



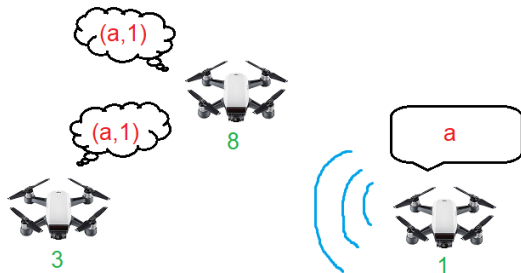
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- Broadcast communication



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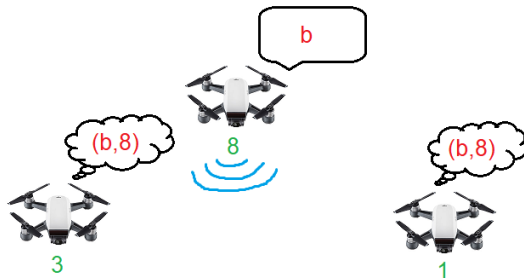
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Execution trace:  $(a, 1)$

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## Distributed setting

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- Broadcast communication
- Uncontrollable actions



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## First order logic

### Example of specification: redundant acknowledgement

Whenever a request is made to an agent, it is later granted by the same agent and a different one.

$$\forall x. \text{request}(x) \Rightarrow \exists y_1, y_2.$$

$$\left( y_1 \sim x \wedge y_2 \not\sim x \wedge \bigwedge_{i \in \{1,2\}} (y_i > x \wedge \text{grant}(y_i)) \right)$$



## Strategy synthesis

### Local strategy

$$(\sigma_{\text{ag}})_{\text{ag} \in \mathcal{A}} : (\Sigma \times \mathcal{A})^* \rightarrow \Sigma_{\text{cont}}$$

or

### Centralized strategy

$$\sigma : (\Sigma \times \mathcal{A})^* \rightarrow \Sigma_{\text{cont}} \times \mathcal{A}$$

## Strategy synthesis

### Local strategy

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↕ Equivalent      ↙ too much info

### Centralized strategy

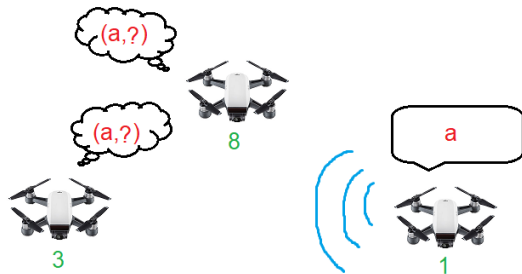
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## Partial information (PI) setting



Execution trace: (a,1)

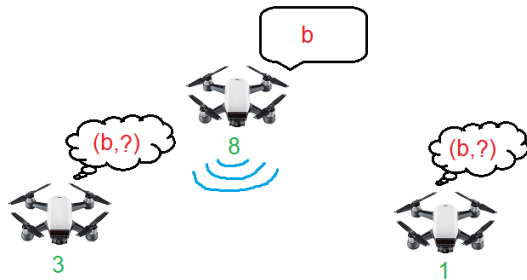
## Partial information (PI) setting



Execution trace: (a,1)

- ▶ Agent 1 p.o.v.: a
- ▶ Agent 3 p.o.v.: a
- ▶ Agent 8 p.o.v.: a

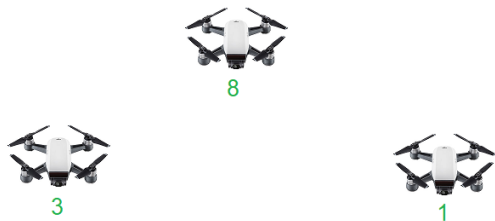
## Partial information (PI) setting



Execution trace: (a,1) (b,8)

- ▶ Agent 1 p.o.v.: a b
- ▶ Agent 3 p.o.v.: a b
- ▶ Agent 8 p.o.v.: a b

## Partial information (PI) setting



Execution trace:  $(a,1) (b,8) \dots \in (\Sigma \times \mathcal{A})^\omega$

▶ Agent 1 p.o.v.:  $\underline{a} b \dots \in (\underline{\Sigma} \cup \Sigma)^\omega$

▶ Agent 3 p.o.v.:  $a b \dots$

▶ Agent 8 p.o.v.:  $a \underline{b} \dots$

## PI synthesis

### PI strategy

$$(\sigma_{\text{ag}})_{\text{ag} \in \mathcal{A}} : (\underline{\Sigma} \cup \Sigma)^* \rightarrow \Sigma_{\text{cont}}$$

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### Counting PI strategy

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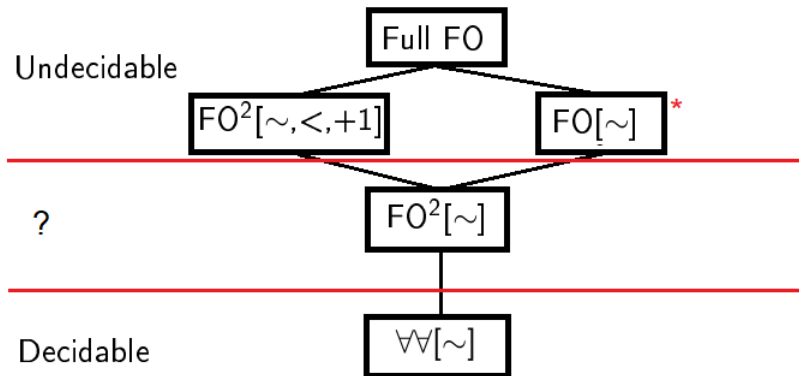
### Counting PI strategy

$$(\sigma_{\text{ag}})_{\text{ag} \in \mathcal{A}} : ((\underline{\Sigma} \cup \Sigma) \rightarrow \mathbb{N}) \rightarrow \Sigma_{\text{cont}}$$

### Fact

Counting PI strategies are strictly weaker than general PI strategies

## (Un)decidability of PI synthesis



\*: even for counting strategies

## What next? (WIP)

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- close gap of decidability; other logics?

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Thank you for listening, any question?

## Formal FO definition

FO

$p := a(x) \mid x < y \mid y = x + 1 \mid x \sim y$   
 $\varphi := p \mid \neg\varphi \mid \varphi \vee \varphi \mid \exists x.\varphi$

"action" (F)      "happens later" (F)      "same agent" (X)  
 "next position" (X)



### Fact

PI strategies are strictly weaker than full info. strategies

### Example

- Environment does two consecutive  $a$  on agents  $ag_1$  and  $ag_2$  (possibly equal),
- then System replies on some agent  $ag_3$  (different from both  $ag_1$  and  $ag_2$ ) either  $eq$  if  $ag_1 = ag_2$ ,  $noteq$  otherwise.

### Intuition

$ag_3$  cannot distinguish between the two cases

## Fact

Counting PI strategies are strictly weaker than general PI strategies

## Example

- System does an  $a$  on some agent  $ag_1$ ,
- then Environment does a  $b$  on  $ag_2$  (can be equal to  $ag_1$ ),
- then System does a  $c_1$  and a  $c_2$  (in any order) on  $ag_1$  again,
- then System does a  $eq$  on  $ag_3$  if  $ag_1 = ag_2$ ,  $noteq$  otherwise.

## Intuition

$ag_1$  does  $c_1$  then  $c_2$  if  $ag_1 = ag_2$ , the other order otherwise